Operational Game Semantics for generative algebraic effects and handlers

(work in progress)

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• Impure behaviour given by operations on computations¹ (e.g choose for non-deterministic choice, raise for exceptions...)

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- Easier to structure compared to combining monadic effects.
- Handlers arise as homomorphisms between models of such algebraic theories.

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Algebraic effects and Handlers, programmatically

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A generalization of exception handlers (constructs such as $try \cdots catch$ or $try \cdots with$) that can capture the *delimited continuation*.

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Example (Global state)

$$E_{state}^{\tau} = \{ \mathbf{set} : \tau \to 1, \mathbf{get} : 1 \to \tau \}$$

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Generally, how to deal with multiple occurences of the same effect type *E* without forefeiting modularity?

The Eff² approach

Use of a distinct identifier (names) ι for each instance of an effect E.

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The Eff² approach

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- Performing an effect: μ#ορ_E V
- Handling an effect: $H = \{ \iota \# op_E \ p \ \kappa \mapsto M \} \ (\iota \# op_E \ case)$

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Programming Language

Syntax: Fine-grained call-by-value

Values
$$V, W \triangleq x \mid \lambda x : \tau.M \mid \iota$$

Terms $M, N \triangleq \mathbf{return} \ V \mid V \mid \mathbf{match} \ V \ \mathbf{with} \ (P_i \to N_i)_{i \in I} \mid \mathbf{let} \ x = M \ \mathbf{in} \ N \mid V \# \mathbf{op} \ W \mid \mathbf{handle} \ M \ \mathbf{with} \ \mathbf{H}$

Handlers $H \triangleq \{\mathbf{return} \ x \mapsto M\} \mid \{V \# \mathbf{op} \ x \ \kappa \mapsto M\} \uplus \mathbf{H}$

ECxts $\mathcal{E} \triangleq \bullet \mid \mathbf{let} \ x = \mathcal{E} \ \mathbf{in} \ M \mid \mathbf{handle} \ \mathcal{E} \ \mathbf{with} \ \mathbf{H}$

Dynamic generation of effects

New construct

Given an effect given by the type (signature) E.

New construct:

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New construct: $M, N \triangleq \cdots \mid new E$

Operational Semantics: (new E; V) \mapsto (return ι ; $V \uplus \{\iota\}$)

Disclosure and contextual equivalence

Consider the following variation of an example from³

 $f(\lambda x.5)$

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Disclosure and contextual equivalence

Consider the following variation of an example from³

$$f(\lambda x.5)$$

$$\simeq_{ctx}$$
let $y = \text{new E in}$
handle
$$f(\lambda x.y \# \text{op}())$$
with $\{\text{return } x \mapsto \text{return } x\}$
 $\{y \# \text{op } x \ \kappa \mapsto \kappa \ 5\}$

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Disclosure and contextual equivalence (cont.)

Now consider a variation of the previous example:

let
$$y = \text{new E in } g y$$
; $f(\lambda x.5)$

Disclosure and contextual equivalence (cont.)

Now consider a variation of the previous example:

let
$$y = \text{new E in } g \ y; f \ (\lambda x.5)$$

$$\not\approx_{ctx}$$
let $y = \text{new E in}$

$$\text{handle}$$

$$g \ y; f \ (\lambda x.y \# \text{op} \ ())$$
with $\{\text{return } x \mapsto \text{return } x\}$

$$\{y \# \text{op } x \ \kappa \mapsto \kappa \ 5\}$$

Operational game semantics model

Adaptation of Lassen's normal-form bisimulation⁴

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Adaptation of Lassen's normal-form bisimulation⁴

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$$\overline{f}(A, c) | f(A, c)$$

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 - Questions:

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(requesting the result of f A as an answer in c)

Answers:

$$\overline{c}(A) \mid c(A)$$

Let's consider the trace of

$$f(\lambda x.5)$$

representing the interaction with the environment given by the evaluation context

let
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Normal Forms:

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The denotation $[\![M]\!]_{\text{ogs}}$ of a given program M is the set of all possible traces generated by M

OGS model for algebraic effects and handlers

Algebraic effects introduce new normal forms:

$$\mathsf{M}_{\mathsf{nf}} = \cdots \mid \mathcal{E}[\iota \# \mathsf{op} \ V]$$
 when $\iota \# \mathsf{op} \notin \mathrm{hdl}(\mathcal{E})$

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Extending the interaction interface with new moves that account for *observable* effectful operations.

But, what counts as observable?

When the program performs an effect

ι#op ₹

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Public: Opponent could potentially handle the effect.

When the program performs an effect

- Public: Opponent could potentially handle the effect.
- Private: Opponent can only forward the effect to any enclosing Player's handling context.

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- ullet observable effect move: $\overline{c}[\iota\#\mathsf{op}\ \mathtt{A}\ \kappa]$
- private effect: $\overline{\mathbf{fwd}}(\kappa)$

• Recall the trace of $M_1 \triangleq f(\lambda x.5)$

$$t_{M_1} = \overline{f}(g,c) \; g(A,d) \; \overline{d}(5) \; c(\text{true})$$

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ullet Recall that the following term is equivalent to ${\tt M}_1$

$$\begin{array}{l} \text{let } y = \text{new E in} \\ \text{handle} \\ \texttt{M}_2 & \triangleq \quad f\left(\lambda x.y\#\text{op}\left(\right)\right) \\ \text{with } \left\{\text{return } x \mapsto \text{return } x\right\} \\ \left\{y\#\text{op } x \; \kappa \mapsto \kappa \; 5\right\} \end{array}$$

Now we look at how M2 interacts with the same environement

$$\mathsf{let}\, f = \big(\lambda g.g \; \mathsf{V}; \mathbf{return} \; \mathsf{true}\big) \; \mathsf{in} \, []$$

Now we look at how M₂ interacts with the same environement

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M₂ evaluates to

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Because of this, we get

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We need a coarser notion of trace equivalence in which

Full-abstraction

Theorem (Soundness) $\simeq_{tr} \ \subseteq \ \simeq_{ctx}$

Full-abstraction

Conclusion

- Contextual equivalence is more subtle in the presence of generativity of first-class effect instances.
- Extending OGS model to account for observable and private effectful behaviour.
- Relaxing trace equivalence to coincide with the contextual one.

QUESTIONS?

References

- [1] Gordon Plotkin and John Power. "Semantics for algebraic operations". In: *Electronic Notes in Theoretical Computer Science* 45 (2001), pp. 332–345.
- [2] Andrej Bauer and Matija Pretnar. "Programming with algebraic effects and handlers". In: Journal of Logical and Algebraic Methods in Programming 84.1 (2015). Special Issue: The 23rd Nordic Workshop on Programming Theory (NWPT 2011) Special Issue: Domains X, International workshop on Domain Theory and applications, Swansea, 5-7 September, 2011, pp. 108–123.
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Operational Semantics

```
(\mathcal{E}[\text{new E}]; \mathcal{V}) \mapsto (\mathcal{E}[\text{return } \iota]; \mathcal{V} \uplus \{\iota\})
           (\mathcal{E}[\mathsf{handle}\;(\mathsf{return}\;\mathsf{V})\;\mathsf{with}\;\mathsf{H}];\mathcal{V})
                                  \mapsto (\mathcal{E}[M\{x := V\}]; \mathcal{V}) when H^{\text{return}} = \{\text{return } x \mapsto M\}
            (\mathcal{E}[\mathsf{handle}\ \mathcal{E}'[\iota \# \mathsf{op}\ V]\ \mathsf{with}\ H]; \mathcal{V})
                        \mapsto (\mathcal{E}[M\{x := V\} \{\kappa := \lambda y. \text{handle } \mathcal{E}'[\text{return } y] \text{ with } H\}]; \mathcal{V})
                    when H^{op} = \{ \iota \# op \times \kappa \mapsto M \}
                    and \iota \# \mathsf{op} \notin \mathsf{hdl}(\mathcal{E}')
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